(Sharing in Linear Logic) and Call-by-Need or Sharing in (Linear Logic and Call-by-Need)

Work in progress with Eduardo Bonelli

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Outline

Introduction

Two computational interpretations for structural rules

Linear sharing logic (MELL_•)

The linear sharing λ -calculus (λ^{\bullet})

Embeddings

Conclusion





	Duplicates	Erases
CBN	arbitrary terms	arbitrary terms
CBV	values	values
CBNd	values	arbitrary terms

Languages that subsume other languages as special cases.

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Examples

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 Call-by-push-value 	Levy
The Bang Calculus	Ehrhard & Guerrieri

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- Explanation of operational mechanisms through simpler primitives.
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- Tackle questions in a uniform and methodical way.

What is the right notion of strong CBNd? What is the right notion of classical CBNd? What is the right quantitative type system for strong CBNd?

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The frameworks above subsume CBN and CBV but not CBNd.

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Completeness fails: $(\operatorname{id} t s)^{\mathsf{V}} \to_{\operatorname{Lin}}^{*} (t s)^{\mathsf{V}}$.

A call-by-need translation

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Sound (but not complete) for CBNd.

$$t \rightarrow^*_{\mathsf{Nd}} s$$
 implies $t^{\mathsf{Nd}} \rightarrow^*_{\mathsf{Aff}} s^{\mathsf{Nd}}$

Goal of this work

Diagnosis

The exponential modalities confuse two different notions:

- 1. Ability to make **copies** of shared subterms.
- 2. Ability to duplicate and erase references to shared subterms.

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duplicating a reference \neq copying

Goal

- 1. Refine Linear Logic to distinguish between these two notions.
- 2. Derive a term calculus unifying CBN, CBV, and CBNd.

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MELL

$A ::= \alpha \mid \overline{\alpha} \mid A \otimes A \mid A^{\mathcal{D}}A \mid !A \mid ?A$

$$A ::= \alpha \mid \overline{\alpha} \mid A \otimes A \mid A \Im A \mid !A \mid ?A$$

$$\frac{}{\vdash A, A^{\perp}} \texttt{ax} \quad \frac{\vdash \Gamma, A \ \vdash \Delta, A^{\perp}}{\vdash \Gamma, \Delta} \texttt{cut}$$

$$\frac{\vdash \Gamma, A \vdash \Delta, B}{\vdash \Gamma, \Delta, A \otimes B} \otimes \quad \frac{\vdash \Gamma, A, B}{\vdash \Gamma, A \, \mathfrak{P} B} \, \mathfrak{P} \quad \frac{\vdash \mathfrak{P}, A}{\vdash \mathfrak{P}, \mathfrak{P}} \, \mathfrak{P}$$

$$\frac{\vdash \Gamma}{\vdash \Gamma, ?A} \le \frac{\vdash \Gamma, ?A, ?A}{\vdash \Gamma, ?A} c \quad \frac{\vdash \Gamma, A}{\vdash \Gamma, ?A} d$$

$$A ::= \alpha \mid \overline{\alpha} \mid A \otimes A \mid A \, \Im \, A \mid !A \mid ?A$$

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$$\frac{\vdash \Gamma, A \vdash \Delta, B}{\vdash \Gamma, \Delta, A \otimes B} \otimes \quad \frac{\vdash \Gamma, A, B}{\vdash \Gamma, A \Im B} \Im \quad \frac{\vdash ?\Gamma, A}{\vdash ?\Gamma, !A} !$$

$$\frac{\vdash \Gamma}{\vdash \Gamma, ?A} = \frac{\vdash \Gamma, ?A, ?A}{\vdash \Gamma, ?A} c \quad \frac{\vdash \Gamma, A}{\vdash \Gamma, ?A} d$$

Structural rules have two possible computational interpretations.

These interpretations are **not** equivalent if one is interested in sharing.

The cloning interpretation

Weakening: erase box



The cloning interpretation

Contraction: duplicate box



The cloning interpretation Dereliction: unbox



The sharing interpretation

Consider a generalized notion of cut:



A *cut** node connects $n \ge 0$ proofs of ?A and a **shared** proof of !A^{\perp}.

The sharing interpretation

Weakening: erase a reference to a shared box


The sharing interpretation

Contraction: duplicate a reference to a shared box



The sharing interpretation

Dereliction: copy box (duplicate & unbox)



The sharing interpretation

Garbage collection: erase box



Summary

	Cloning	Sharing
Weakening	erase box	erase reference
Contraction	duplicate box	duplicate reference
Dereliction	unbox	copy box (duplicate & unbox)
(Garbage collection)		erase box

Summary

	Cloning	Sharing
Weakening	erase box	erase reference
Contraction	duplicate box	duplicate reference
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(Garbage collection)		erase box

CBNd cannot copy arbitrary shared subterms.

To understand CBNd:

- We adopt the point of view of sharing.
- To restrict duplication of boxes: we consider a variant of MELL with restricted dereliction.

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Formulae are extended with two operators \bullet and \circ .

$$A ::= \alpha \mid \overline{\alpha} \mid A \otimes A \mid A \Im A \mid !A \mid ?A \mid \bullet A \mid \circ A$$
$$(\bullet A)^{\perp} = \circ A^{\perp} \quad (\circ A)^{\perp} = \bullet A^{\perp}$$

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Two new rules:

$\vdash \Gamma, A$	$\vdash \Gamma, A$
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The dereliction rule is replaced by:

$$\frac{\vdash \Gamma, \circ A}{\vdash \Gamma, ? \circ A} d \circ$$

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$$A \sim - \circ \bullet A \qquad \text{but} \qquad !A \sim - \circ ! \bullet A \qquad ! \text{ and } ? \text{ are not monotonic}$$

Intuition: a box may be copied only if there is a \bullet node immediately next to the promotion node.



Theorem (Cut elimination)

For any MELL_{\bullet} proof there is a cut-free proof of the same conclusion.

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For any MELL_• proof there is a cut-free proof of the same conclusion. *Proof.*

- 1. Extend MELL. with the (admissible) cut* rule.
- 2. Prove cut + cut* elimination.



Theorem (Conservative extension)

 $\label{eq:constraint} \begin{array}{ll} \vdash \Gamma \text{ holds in MELL} & \text{if and only if} & \vdash \Gamma^\bullet \text{ holds in MELL}_\bullet \\ & \text{where } \Gamma^\bullet := \Gamma\{! \mapsto !\bullet, ? \mapsto ?\circ\}. \end{array}$

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(⇒) The following rules are admissible in MELL_•: $\frac{\vdash ?\circ\Gamma, A}{\vdash ?\circ\Gamma, !\bullet A} !\bullet \quad \frac{\vdash \Gamma}{\vdash \Gamma, ?\circ A} ?\circ w \quad \frac{\vdash \Gamma, ?\circ A, ?\circ A}{\vdash \Gamma, ?\circ A} ?\circ c \quad \frac{\vdash \Gamma, A}{\vdash \Gamma, ?\circ A} ?\circ d$ (⇐) Any MELL_• proof is valid in MELL erasing • and •.

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MELL. refines MELL.

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MELL, suggests the definition of a term calculus, inspired also by:

- 1. Many linear λ -calculi Lafont, Wadler, Pfenning, ...
- 2. The Linear Substitution Calculus
- 3. The Bang Calculus

Accattoli & Kesner

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Syntax of terms

t

(linear vs. unrestricted variables) (abstractions bind linear variables)

(ESs bind unrestricted variables)

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font, Wadler, Pfenning, ... Accattoli & Kesner Ehrhard & Guerrieri The linear sharing $\lambda\text{-calculus}$ — Type system Types and typing judgments

$$A ::= \alpha \mid A \multimap B \mid \bullet A \mid !A \qquad \qquad \left| \Delta; \Gamma \vdash t : A \right|$$

(1) Types in Δ are implicitly prefixed by !•. (2) Γ is treated linearly.

The linear sharing $\lambda\text{-calculus}$ — Type system Types and typing judgments

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$$\frac{\overline{\Delta}; a: A \vdash a: A}{\overline{\Delta}; r \vdash a: A} \stackrel{\text{ax}}{=} \frac{\overline{\Delta}; \Gamma_1 \vdash t: A \multimap B}{\overline{\Delta}; \Gamma_1 \vdash t: A \multimap B} \stackrel{\text{der}}{=} \frac{\Delta; \Gamma_1 \vdash t: A \multimap B}{\overline{\Delta}; \Gamma_1, \Gamma_2 \vdash ts: B} \stackrel{\text{oe}}{=} \frac{\Delta; \Gamma \vdash t: A}{\overline{\Delta}; \Gamma \vdash \bullet t: \bullet A} \stackrel{\text{oi}}{=} \frac{\Delta; \Gamma \vdash t: \bullet A}{\overline{\Delta}; \Gamma \vdash \circ (t): A} \stackrel{\text{oe}}{=} \frac{\Delta; \cdot \vdash t: A}{\overline{\Delta}; \cdot \vdash t: A} \stackrel{\text{i}}{=} \frac{\Delta; X: A; \Gamma_1 \vdash t: B}{\overline{\Delta}; \Gamma \vdash \circ (t): A} \stackrel{\text{oe}}{=} \frac{\Delta; \cdot \vdash t: A}{\overline{\Delta}; \cdot \vdash t: A} \stackrel{\text{i}}{=} \frac{\Delta; X: A; \Gamma_1 \vdash t: B}{\overline{\Delta}; \Gamma_1, \Gamma_2 \vdash t[X \setminus s]: B} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A} \stackrel{\text{oe}}{=} \frac{\Delta; \tau \vdash t: A}{\overline{\Delta}; \tau \vdash t: A}$$

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$$A ::= \alpha \mid A \multimap B \mid \bullet A \mid !A \qquad \left| \Delta; \Gamma \vdash t : A \right|$$

(1) Types in Δ are implicitly prefixed by !•. (2) Γ is treated linearly. Typing rules

 $\frac{1}{\Delta; a: A \vdash a: A} \text{ ax } \frac{1}{\Delta, x: A: \cdot \vdash x: \bullet A} \text{ der}$ $\frac{\Delta; \Gamma, a: A \vdash t: B}{\Delta; \Gamma \vdash \lambda a. t: A \multimap B} \multimap i \quad \frac{\Delta; \Gamma_1 \vdash t: A \multimap B \quad \Delta; \Gamma_2 \vdash s: B}{\Delta; \Gamma_1, \Gamma_2 \vdash ts: B}$ $\frac{\Delta; \Gamma \vdash t : A}{\Delta; \Gamma \vdash \bullet t : \bullet A} \bullet i \quad \frac{\Delta; \Gamma \vdash t : \bullet A}{\Delta; \Gamma \vdash o(t) : A} \bullet e$ $\frac{\Delta; \cdot \vdash t : A}{\Delta; \cdot \vdash !t : !A} ! i \quad \frac{\Delta; x : A; \Gamma_1 \vdash t : B \quad \Delta; \Gamma_2 \vdash s : ! \bullet A}{\Delta; \Gamma_1, \Gamma_2 \vdash t[x \setminus s] : B}$ lee

Substitution contexts

$L ::= \Box | L[x \setminus t]$ tL plugs t in L

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Reduction rules (without "L" contexts)

$$\begin{array}{rcl} (\lambda a. t) \, s & \rightarrow_{\bullet db} & t\{a \setminus s\} \\ \circ(\bullet t) & \rightarrow_{\bullet open} & t \\ C\langle x \rangle [x \setminus ! \bullet t] & \rightarrow_{\bullet ls} & C\langle \bullet t \rangle [x \setminus ! \bullet t] \\ t[x \setminus ! s] & \rightarrow_{\bullet gc} & t & \text{if } x \notin fv(t) \end{array}$$

Substitution contexts

 $L ::= \Box \mid L[x \setminus t]$ tL plugs t in L

Reduction rules

$$\begin{array}{rcl} (\lambda a. t) L s & \rightarrow_{\bullet db} & t\{a \backslash s\} L \\ o((\bullet t) L) & \rightarrow_{\bullet open} & tL \\ C\langle x \rangle [x \backslash (!(\bullet t) L_1) L_2] & \rightarrow_{\bullet is} & C\langle (\bullet t) L_1 \rangle [x \backslash !(\bullet t) L_1] L_2 \\ & t[x \backslash (!s) L] & \rightarrow_{\bullet gc} & tL & \text{if } x \notin fv(t) \end{array}$$

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Example $o(x[x \setminus ! \bullet y]) \rightarrow_{\bullet \mathsf{ls}} o((\bullet y)[x \setminus ! \bullet y]) \rightarrow_{\bullet \mathsf{open}} y[x \setminus ! \bullet y] \rightarrow_{\bullet \mathsf{gc}} y$

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Example $o(x[x \setminus ! \bullet y]) \rightarrow_{\bullet \mathsf{ls}} o((\bullet y)[x \setminus ! \bullet y]) \rightarrow_{\bullet \mathsf{open}} y[x \setminus ! \bullet y] \rightarrow_{\bullet \mathsf{gc}} y$

 $\boldsymbol{z}[\boldsymbol{x} \backslash \boldsymbol{y}] \text{ and } \boldsymbol{x}[\boldsymbol{x} \backslash \boldsymbol{!} \boldsymbol{y}] \text{ are normal forms}$

Proposition (Soundness wrt MELL_•) If $\Delta; \Gamma \vdash t : A$ then $\vdash ? \circ \Delta^{\perp}, \Gamma^{\perp}, A$ in MELL_•. Proposition (Soundness wrt MELL_•) If $\Delta; \Gamma \vdash t : A$ then $\vdash ? \circ \Delta^{\perp}, \Gamma^{\perp}, A$ in MELL_•. Proposition (Subject reduction) If $\Delta; \Gamma \vdash t : A$ and $t \rightarrow s$ then $\Delta; \Gamma \vdash s : A$.

Harder than we expected.

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First attempt

Apply Tait–Martin-Löf's technique. $(\rightarrow \subseteq \Rightarrow \subseteq \rightarrow^*) + \Diamond(\Rightarrow)$ Defining an inductive notion of simulatenous reduction \Rightarrow is very difficult.

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First attempt

 $\begin{array}{ll} \mbox{Apply Tait-Martin-Löf's technique.} & (\to \subseteq \Rightarrow \subseteq \to^*) + \Diamond (\Rightarrow) \\ \mbox{Defining an inductive notion of simulatenous reduction } \Rightarrow \mbox{ is very difficult.} \end{array}$

Second attempt

Use techniques based on residuals (Lévy, Huet, Melliès). FD + PERM PERM fails:

$$\begin{aligned} & z[x \setminus !y][y \setminus (! \bullet t)L] \xrightarrow{\bullet \mathsf{ls}} z[x \setminus ! \bullet t][y \setminus ! \bullet t]L \\ & \bullet_{\mathsf{gc}} \downarrow & \bullet_{\mathsf{gc}} \downarrow \\ & z[y \setminus (! \bullet t)L] & z[y \setminus ! \bullet t]L \end{aligned}$$

Definition (Structural equivalence)

Structural equivalence is the congruence generated by:

 $t[x \backslash s[y \backslash r]] \equiv t[x \backslash s][y \backslash r]$

Lemma (Strong bisimulation) $(\equiv \rightarrow) \subseteq (\rightarrow \equiv)$ Theorem (Confluence) λ^{\bullet} is CR up to \equiv :




The Linear Substitution Calculus (LSC) $(\lambda x. t)L s \rightarrow_{db} t[x \setminus s]L \quad C\langle x \rangle [x \setminus t] \rightarrow_{ls} C\langle t \rangle [x \setminus t]$ $t[x \setminus s] \rightarrow_{gc} t \quad (x \notin fv(t))$

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Fact. Simply typed LSC is SN. (db-expansion + SN of STLC + PSN)

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Fact. Simply typed LSC is SN. (db-expansion + SN of STLC + PSN) **Idea.** From $t_1 \rightarrow_{\bullet} t_2 \rightarrow_{\bullet} \dots$ obtain $\llbracket t_1 \rrbracket \rightarrow_{\mathsf{lsc}} \llbracket t_2 \rrbracket \rightarrow_{\mathsf{lsc}} \dots$

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$$(\lambda x. t) L s \rightarrow_{db} t[x \setminus s] L \quad C\langle x \rangle [x \setminus t] \rightarrow_{ls} C\langle t \rangle [x \setminus t]$$

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Problem: mismatch between \rightarrow_{\bullet} and $\rightarrow_{\mathsf{lsc}}$ reduction

$$\begin{array}{ll} x[x \setminus (! \bullet t) L] & \to_{\bullet} & (\bullet t)[x \setminus ! \bullet t] L \\ x[x \setminus t L] & \to_{\mathsf{lsc}} & (t L)[x \setminus t L] \end{array}$$

The Linear Substitution Calculus (LSC) $(\lambda x. t)L s \rightarrow_{db} t[x \setminus s]L \quad C\langle x \rangle [x \setminus t] \rightarrow_{ls} C\langle t \rangle [x \setminus t]$ $t[x \setminus s] \rightarrow_{gc} t \quad (x \notin fv(t))$

Fact. Simply typed LSC is SN. (db-expansion + SN of STLC + PSN) **Idea.** From $t_1 \rightarrow \bullet t_2 \rightarrow \bullet \ldots$ obtain $[t_1] \rightarrow_{lsc} [t_2] \rightarrow_{lsc} \ldots$

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$$\begin{array}{lll} x[x \setminus (! \bullet t) L] & \to & (\bullet t)[x \setminus ! \bullet t] L \\ x[x \setminus tL] & \to_{\mathsf{lsc}} & (tL)[x \setminus tL] & \Longrightarrow & t[x \setminus t] L \end{array}$$

The Linear Substitution Calculus (LSC) $(\lambda x. t)L s \rightarrow_{db} t[x \setminus s]L \quad C\langle x \rangle [x \setminus t] \rightarrow_{ls} C\langle t \rangle [x \setminus t]$ $t[x \setminus s] \rightarrow_{gc} t \quad (x \notin fv(t))$

Fact. Simply typed LSC is SN. (db-expansion + SN of STLC + PSN) **Idea.** From $t_1 \rightarrow \bullet t_2 \rightarrow \bullet \ldots$ obtain $\llbracket t_1 \rrbracket \rightarrow_{\mathsf{lsc}} \llbracket t_2 \rrbracket \rightarrow_{\mathsf{lsc}} \ldots$

Problem: mismatch between \rightarrow_{\bullet} and $\rightarrow_{\mathsf{lsc}}$ reduction

$$\begin{array}{lll} & x[x \setminus (! \bullet t) L] & \to & (\bullet t)[x \setminus ! \bullet t] L \\ & x[x \setminus t L] & \to_{\mathsf{lsc}} & (t L)[x \setminus t L] & \Rightarrow & t[x \setminus t] L \end{array}$$

Definition (Fusion)

$$\begin{array}{rcl} t[y \backslash s][x \backslash s] & \Rightarrow & t\{y \backslash x\}[x \backslash s] \\ C\langle t[x \backslash s] \rangle & \Rightarrow & C\langle t\rangle[x \backslash s] \end{array}$$

Lemma (Postponement) $(\Rightarrow \rightarrow_{\mathsf{lsc}}) \subseteq (\rightarrow_{\mathsf{lsc}} \Rightarrow)$

Theorem (Strong normalization) The typed λ^{\bullet} -calculus is SN. *Proof.*

Theorem (Strong normalization)

The typed λ^{\bullet} -calculus is SN.

Proof. Translate typable λ^{\bullet} terms to typable LSC terms:

 $\begin{bmatrix} A \multimap B \end{bmatrix} := \begin{bmatrix} A \end{bmatrix} \rightarrow \begin{bmatrix} B \end{bmatrix} \qquad \begin{bmatrix} \bullet A \end{bmatrix} := \bigstar \rightarrow \begin{bmatrix} A \end{bmatrix} \qquad \begin{bmatrix} !A \end{bmatrix} := \begin{bmatrix} A \end{bmatrix}$ $\begin{bmatrix} a \end{bmatrix} := a \qquad \begin{bmatrix} x \end{bmatrix} := x \\ \begin{bmatrix} \lambda a. t \end{bmatrix} := \lambda a. \begin{bmatrix} t \end{bmatrix} \qquad \begin{bmatrix} t \end{bmatrix} \qquad \begin{bmatrix} t s \end{bmatrix} := \begin{bmatrix} t \end{bmatrix} \begin{bmatrix} s \end{bmatrix} \\ \begin{bmatrix} \bullet t \end{bmatrix} := \lambda z. \begin{bmatrix} t \end{bmatrix} \qquad (z \text{ fresh}) \qquad \begin{bmatrix} o(t) \end{bmatrix} := \begin{bmatrix} t \end{bmatrix} * \\ \begin{bmatrix} !t \end{bmatrix} := \begin{bmatrix} t \end{bmatrix} \qquad \begin{bmatrix} t \end{bmatrix} \begin{bmatrix} x \end{bmatrix}$

Map an infinite t₁ → t₂ → ... to [[t₁]] →_{lsc} ⇒ [[t₂]] →_{lsc} ⇒
 Postpone ⇒ to obtain an infinite reduction sequence in LSC.
 (Strictly speaking, we also need to postpone →_{•gc}).

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Notions of reduction

A zoo of rewriting rules

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Definition: notions of CBN, CBV, and CBNd

$$\begin{array}{l} \rightarrow_{\mathsf{N}} := \rightarrow_{db} \cup \rightarrow_{\mathsf{ls}} \cup \rightarrow_{gc} \\ \\ \rightarrow_{\mathsf{V}} := \rightarrow_{db} \cup \rightarrow_{\mathsf{lsv}} \cup \rightarrow_{gcv^{+}} \quad \rightarrow_{\mathsf{V}^{+}} := \rightarrow_{db} \cup \rightarrow_{\mathsf{lsv}^{+}} \cup \rightarrow_{gcv^{+}} \\ \\ \rightarrow_{\mathsf{Nd}} := \rightarrow_{db} \cup \rightarrow_{\mathsf{lsv}} \cup \rightarrow_{gc} \quad \rightarrow_{\mathsf{Nd}^{\times}} := \rightarrow_{db} \cup \rightarrow_{\mathsf{lsv}^{\times}} \cup \rightarrow_{gc} \end{array}$$

Embedding CBN, CBV, CBNd

	CBN	CBV ⁺	CBV	$CBNd^{\times}$	CBNd
$A \rightarrow B$!•A∘ B	!•A∘ !•B	!•A —∘ !•B	!• <i>A</i> ⊸ • <i>B</i>	_

Embedding CBN, CBV, CBNd

	CBN	CBV ⁺	CBV	$CBNd^{ imes}$	CBNd
$A \rightarrow B$!•A ⊸ B	!•A∘ !•B	!•A —∘ !•B	!• <i>A</i> ⊸ • <i>B</i>	_
x	o(x)	!●o(x)	!x	x	_
$\lambda x. t$	$\lambda a. t[x \setminus a]$	$! \bullet \lambda a. t[x \setminus a]$	$!\bullet\lambda a.t[x \setminus a]$	• $\lambda a. t[x \setminus a]$	_
ts	t (!•s)	$o(x)[x \setminus t] s$	$o(x)[x \setminus t] s$	o(t)(!s)	_
$t[x \setminus s]$	$t[x \setminus ! \bullet s]$	$t[x \setminus s]$	$t[x \setminus s]$	$t[x \setminus !s]$	-

Embedding CBN, CBV, CBNd

	CBN	CBV ⁺	CBV	$CBNd^{ imes}$	CBNd
A ightarrow B	!• <i>A</i> ⊸ <i>B</i>	!•A∘ !•B	!•A —∘ !•B	!• <i>A</i> ⊸ • <i>B</i>	_
x	o(x)	!●o(x)	!x	x	_
λx.t	$\lambda a. t[x \setminus a]$	$!\bullet\lambda a. t[x \setminus a]$	$!\bullet\lambda a.t[x \setminus a]$	• $\lambda a. t[x \setminus a]$	_
ts	t (!•s)	$o(x)[x \setminus t] s$	$o(x)[x \setminus t] s$	o(t)(!s)	-
$t[x \setminus s]$	$t[x \setminus ! \bullet s]$	$t[x \setminus s]$	$t[x \setminus s]$	$t[x \setminus !s]$	_

Theorem (Soundness/completeness) The above embeddings are:

Sound and complete for reduction.
Sound for reduction but not complete.
Sound for reduction and complete for equality.
Sound and complete for reduction.
(Does not seem possible)

Embedding the Bang calculus

The Bang Calculus

(Bucciarelli *et al.*'s
$$\lambda$$
! with linear subst.)

$$\begin{array}{lll} A ::= \alpha \mid !A \mid !A \to B & t ::= x \mid \lambda x. \ t \mid t \ s \mid !t \mid \operatorname{der}(t) \mid t[x \setminus s] \\ & (\lambda x. \ t) L \ s \quad \rightarrow_{\operatorname{db}} & t[x \setminus s] L \\ & C\langle x \rangle [x \setminus (!s) L] \quad \rightarrow_{\operatorname{ls!}} & C\langle s \rangle [x \setminus !s] L \\ & t[x \setminus (!s) L] \quad \rightarrow_{\operatorname{gc!}} & tL & \operatorname{if} x \notin \operatorname{fv}(t) \\ & \operatorname{der}((!t) L) \quad \rightarrow_{\operatorname{d!}} & tL \end{array}$$

1

Embedding the Bang calculus

The Bang Calculus

(Bucciarelli *et al.*'s
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! with linear subst.)

$$\begin{array}{lll} A ::= \alpha \mid !A \mid !A \to B & t ::= x \mid \lambda x. \ t \mid t \ s \mid !t \mid \operatorname{der}(t) \mid t[x \setminus s] \\ & (\lambda x. \ t) L \ s \quad \rightarrow_{\operatorname{db}} & t[x \setminus s] L \\ & C\langle x \rangle [x \setminus (!s) L] \quad \rightarrow_{\operatorname{ls!}} & C\langle s \rangle [x \setminus !s] L \\ & t[x \setminus (!s) L] \quad \rightarrow_{\operatorname{gc!}} & tL & \operatorname{if} x \notin \operatorname{fv}(t) \\ & \operatorname{der}((!t) L) \quad \rightarrow_{\operatorname{d!}} & tL \end{array}$$

Theorem

The following embedding is sound and complete for reduction, up to identifying $der(t) \equiv x[x \setminus t]$:

Strategies

The embeddings above are for calculi. We are also working on embedding strategies.

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Idea

- $t[x \setminus s] \quad \longrightarrow \quad \text{evaluate inside } s \text{ until the outermost } !... appears$
- $t[x \setminus !s] \longrightarrow$ evaluate t until x is needed
- $(...x..)[x \setminus s] \longrightarrow$ evaluate inside *s* until the outermost \bullet ... appears
- $(...x...)[x \setminus ! \bullet s] \quad \rightsquigarrow \quad \text{perform the substitution}$

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CBNCBVCBNd×
$$t[x \setminus ! \bullet s]$$
 $t[x \setminus s]$ $t[x \setminus !s]$

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- ▶ MELL_•: a variant of MELL with restricted dereliction.
- λ^{\bullet} : a derived linear λ -calculus with controlled sharing.
- Embeddings of CBN, CBV, CBNd, Bang calculus.

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- ▶ MELL_•: a variant of MELL with restricted dereliction.
- λ^{\bullet} : a derived linear λ -calculus with controlled sharing.
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Ongoing/future work

- Embeddings of families of strategies: weak, head, open, strong, etc.
- MELL_•: proof nets.
 In this talk, proof nets were used just for intuition.
 Cut elimination in sequent calculus MELL_• does not actually share.
- MELL_•: models.

E.g. adapting phase or coherence semantics is not obvious.

• Theory of λ^{\bullet} : confluence, standardization, solvability, etc.